# On the finite time extinction phenomenon for some nonlinear fractional evolution equations

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#### Outline

The general problem Our Problem Some previous results on Fractional Calculus The finite time extinction phenomenon Conclusions

# **Outline of Topics**

#### The general problem

A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

#### Our Problem

Aim of the work

#### Some previous results on Fractional Calculus

Lemmas

Numerical examples

The finite time extinction phenomenon

The main Theorem Sketch of the proof Remarks

#### Conclusions

A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

## A fractional evolution boundary value problem

Let  $\Omega \subset \mathbb{R}^N$ ,  $N \geq 1$ , be a general open set. Let  $Q_{\infty} = \Omega \times (0, +\infty)$ ,  $\Sigma_{\infty} = \partial \Omega \times (0, +\infty)$ , and consider a fractional evolution boundary value problem formulated as follows:

$$\begin{cases} a_1 \frac{\partial u}{\partial t} + a_\alpha \frac{\partial^\alpha u}{\partial t^\alpha} + Au &= f(x, t) \quad \text{in } Q_\infty, \\ Bu &= g(x, t) \quad \text{on } \Sigma_\infty, \\ u(x, 0) &= u_0(x) \quad \text{in } \Omega. \end{cases}$$
(1)

▶ 
$$a_1 \ge 0$$
,  $a_\alpha > 0$ ,  $\alpha \in (0,1)$ 

▶  $\partial^{\alpha}/\partial t^{\alpha}$  is the Riemann-Liouville fractional derivative:

$$\frac{\partial}{\partial t^{\alpha}}u(x,t)=\frac{\partial}{\partial t}\frac{1}{\Gamma(1-\alpha)}\int_{0}^{t}\frac{u(x,\tau)}{(t-\tau)^{\alpha}}d\tau$$

A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

# A fractional evolution boundary value problem

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- ► Au denotes a nonlinear operator (usually in terms of u and the partial differentials of u),
- Bu denotes a boundary operator
- the data f(x, t), g(x, t) and  $u_0(x)$  are given functions
- ▶ for simplicity, A and B are assumed to be autonomous operators, i.e., with time independent coefficients.



A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

### Stabilization of a solution: main task

In the study of the stabilization of solutions:



A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

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In the study of the stabilization of solutions:

▶ it is usually assumed that:

 $f(x,t) 
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ightarrow g_\infty(x) \quad ext{as} \ t 
ightarrow +\infty,$ 

in some functional spaces



A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

### Stabilization of a solution: main task

In the study of the stabilization of solutions:

the main task is to prove that

$$u(x,t) \rightarrow u_{\infty}(x) \text{ as } t \rightarrow +\infty,$$

in some topology of a suitable functional space, with  $u_{\infty}(x)$  solution of

$$\begin{cases} Au_{\infty} &= f_{\infty}(x) \quad \text{in } \Omega, \\ Bu_{\infty} &= g_{\infty}(x) \quad \text{on } \partial\Omega. \end{cases}$$

- This has been the most recurrent approach in the literature:
- Ph. Clément, R.C. MacCamy, J.A. Nohel, Asymptotic Properties of Solutions of Nonlinear Abstract Volterra Equations, J. Int. Eq., 3, 185-216, 1981.



A fractional evolution boundary value problem Stabilization of a solution Extinction in finite time

### A stronger property: extinction in finite time

• Starting by assuming that A0 = 0, B0 = 0 and

$$egin{aligned} f(x,t) &= 0 \quad \forall \ t \geq T_f, \ g(x,t) &= 0 \quad \forall \ t \geq T_g, \end{aligned}$$

for some  $\mathit{T_f} < \infty$  and  $\mathit{T_g} < \infty$ 



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for some  $\mathit{T_f} < \infty$  and  $\mathit{T_g} < \infty$ 

we want to arrive to the following natural phenomenon of the extinction in finite time:

### Definition

Let u be a solution of the evolution boundary value problem (1). We will say that u(x, t) possesses the property of extinction in a finite time if there exists  $t^* < \infty$  such that

$$u(x,t) \equiv 0 \text{ on } \Omega, \ \forall \ t \geq t^*.$$

## The problem under study

Let us consider the following family of general problems:

$$(\mathcal{P}) \left\{ \begin{array}{rl} a_1 \frac{\partial u}{\partial t} + a_\alpha \frac{\partial^\alpha u}{\partial t^\alpha} - \operatorname{div} \left( |\nabla u|^{p-2} \nabla u \right) + \beta(u) = f \quad \text{in} \quad Q_\infty \\ u = 0 \quad \text{on} \ \Sigma_\infty \\ u(x, 0) = u_0(x) \quad \text{in} \quad \Omega. \end{array} \right.$$

where  $a_1 \geq 0$ ,  $a_\alpha > 0$ ,  $\alpha \in (0, 1)$  and p > 1.



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where  $a_1 \geq 0$ ,  $a_\alpha > 0$ ,  $\alpha \in (0, 1)$  and p > 1.

In actual fact, if a<sub>1</sub> = 0 the initial condition must be understood as follows:

$$\lim_{t\to 0} \Gamma(\alpha)t^{1-\alpha}u(x,t) = \lim_{t\to 0} (I_t^{1-\alpha}u)(x,t) = u_0(x).$$



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where  $a_1 \geq 0$ ,  $a_\alpha > 0$ ,  $\alpha \in (0,1)$  and p > 1.

- When p = 2, div  $(|\nabla u|^{p-2} \nabla u) = \Delta u$
- β(u) is the equivalent of the "feedback" term in the control theory.



# The problem under study

Let us consider the following family of general problems:

$$(\mathcal{P}) \left\{ \begin{array}{rl} a_1 \frac{\partial u}{\partial t} + a_\alpha \frac{\partial^\alpha u}{\partial t^\alpha} - \operatorname{div} \left( |\nabla u|^{p-2} \nabla u \right) + \beta(u) = f \quad \text{in} \quad Q_\infty \\ \\ u = 0 \quad \text{on} \ \Sigma_\infty \\ \\ u(x, 0) = u_0(x) \quad \text{in} \quad \Omega. \end{array} \right.$$

where  $a_1 \geq 0$ ,  $a_\alpha > 0$ ,  $\alpha \in (0, 1)$  and p > 1.

- These problems arise in many contexts, as e.g. the study of the nonlinear reaction-diffusion equation with absorption, or in the heat conduction in materials with memory. See e.g.:
  - J.W. Nunziato, On heat conduction in materials with memory, Q. Appl. Math., 29, 187-304, 1971.



Under suitable conditions, we shall prove that the solution to  $(\mathcal{P})$  satisfies an integral energy inequality leading to its extinction in a finite time.





Concretely:

We will first prove the occurrence of the extinction in finite time for the problem (1) with a₁ > 0 and aα > 0.





# Aims

Concretely:

We will first prove the occurrence of the extinction in finite time for the problem (1) with a₁ > 0 and aα > 0.

Then, we will pass to consider the limit problem obtained when a<sub>1</sub> = 0 and a<sub>α</sub> > 0.

This is the most extraordinary case, since we prove that the finite time extinction phenomenon still appears, even with a non-smooth profile near the extinction time.



Lemmas Numerical examples

### Lemma1

#### Lemma

Let  $\alpha \in (0,1)$  and  $u \in C^0([0,T]:\mathbb{R})$ ,  $u' \in L^1(0,T:\mathbb{R})$  and u monotone. Then

$$2 u(t) rac{d^{lpha} u}{dt^{lpha}}(t) \geq rac{d^{lpha} u^2}{dt^{lpha}}(t), \qquad ext{a.e.} \ t \in (0, T].$$



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### Lemma1

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#### Remarks:

- the inequality (2) can be trivially checked if  $\alpha = 1$ .
- we conjecture that inequality (2) still holds true under weaker hypothesis on u (avoiding the monotonicity).

Lemmas Numerical examples

 Inequality (2) allows to conclude the monotonicity (or accretiveness) of the fractional differential operator in a very direct way.



Lemmas Numerical examples

- Inequality (2) allows to conclude the monotonicity (or accretiveness) of the fractional differential operator in a very direct way.
- The proof of the monotonicity has been already provided in the literature by means of very sophisticated arguments. See e.g:
  - G. Gripenber, Volterra integro-differential equations with accrettive nonlinearity, J. Differential Eqs., 60, 57-79, 1985
  - PH. Clément and J. Prüss, Completely positive measures and Feller semigroups, Math. Ann., 287, 73-105, 1990
  - PH. Clément and S.O. Londen, On the sum of fractional derivatives and m-accretive operators, in Partial Differential Equation Models in Physics and Biology, Vol.82, G. Lumer and S. Nicaise and B.W. Schulze (Eds.), Akademie Verlag, 91-100, 1994



Lemmas Numerical example

### Lemma2: a more general version of Lemma 1

#### Lemma

Given the Hilbert space H, let  $\alpha \in (0, 1)$  and  $u \in L^{\infty}(0, T : H)$ such that  $\frac{d^{\alpha}}{dt^{\alpha}}u \in L^{1}(0, T : H)$ . Assume that  $||u(\cdot)||_{H}$  is non-increasing (i.e.  $||u(t_{2})||_{H} \leq ||u(t_{1})||_{H}$  for a.e.  $t_{1}, t_{2} \in (0, T)$ such that  $t_{1} \leq t_{2}$ ). Then, there exists  $k(\alpha) > 0$  such that for almost every  $t \in (0, T)$  we have that

$$\left(u(t), \frac{d^{\alpha}}{dt^{\alpha}}u(t)\right)_{H} \ge k(\alpha) \frac{d^{\alpha}}{dt^{\alpha}} \|u(t)\|_{H}^{2}.$$
 (3)



Lemmas Numerical example

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Lemmas Numerical examples

### Lemma2: a more general version of Lemma 1

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Lemmas Numerical examples

### Lemma2: a more general version of Lemma 1

$$\left(u(t), \frac{d^{lpha}}{dt^{lpha}}u(t)
ight)_{H} \geq k(lpha) \, \frac{d^{lpha}}{dt^{lpha}} \|u(t)\|_{H}^{2}.$$

- ▶ Inequality (4) directly implies  $\frac{d^{\alpha}}{dt^{\alpha}} ||u(t)||_{H}^{2} \in L^{1}(0, +\infty)$ , which is not straightforward to see
- In the literature, it had been already shown (by many authors) that:

$$\int_0^t u(t) rac{d^lpha}{dt^lpha} u(t) dt \geq \int_0^t |u(t)|^2 dt$$

Ph. Clément, R.C. MacCamy, J.A. Nohel, Asymptotic Properties of Solutions of Nonlinear Abstract Volterra Equations, J. Int. Eq., 3, 185-216, 1981.



Lemmas Numerical examples

### Numerical examples



Figure: Function  $\frac{d^{\alpha}u^{2}}{dt^{\alpha}}(t)$  vs.  $2u(t)\frac{d^{\alpha}u}{dt^{\alpha}}(t)$  for  $t \in (0, 5]$ .,  $u(t) = e^{5/(1+t^{2})}$  and different values of  $\alpha$ .

Lemmas Numerical examples

### Numerical examples



Figure: Function  $\frac{d^{\alpha}u^{2}}{dt^{\alpha}}(t)$  vs.  $2u(t)\frac{d^{\alpha}u}{dt^{\alpha}}(t)$  for  $t \in (0, 5]$ .,  $u(t) = t^{2} - 5$  and different values of  $\alpha$ .



Lemmas Numerical examples

### Numerical examples



Figure: Function  $\frac{d^{\alpha}u^{2}}{dt^{\alpha}}(t)$  vs.  $2u(t)\frac{d^{\alpha}u}{dt^{\alpha}}(t)$  for  $t \in (0, 5]$ .,  $u(t) = \sin(t)$  and different values of  $\alpha$ .



The main Theorem Sketch of the proof Remarks

### The finite time extinction phenomenon

#### Theorem

Let  $\beta(\cdot)$  be any nondecreasing continuous function such that  $\beta(0)=0.$ Then, for any  $f \in L^1_{loc}(0, +\infty : L^2(\Omega))$  and  $u_0 \in L^2(\Omega)$ , there exists a weak solution of the problem  $(\mathcal{P})$ . Assume also that  $\beta(s) = |s|^{\sigma-1}s$  for some  $\sigma > 0$  such that either p < 2 and  $\sigma > 0$  arbitrary, or  $\sigma < 1$  and p > 1 arbitrary. Additionally, let  $u_0 \in H^2(\Omega)$ ,  $u_0 \in L^{2\sigma}(\Omega)$  and  $f \in H^1_{loc}(0, +\infty : L^2(\Omega))$  satisfying that  $\exists t_f \geq 0$  such that  $f(x,t) \equiv 0$  a.e.  $x \in \Omega$  and a.e.  $t > t_f$ . Then, there exists  $t_0 \ge t_f \ge 0$  such that  $u(x, t) \equiv 0$  for a.e.  $x \in \Omega$ and for any  $t \geq t_0$ .

The main Theorem Sketch of the proof Remarks

# Proof of the existence

The existence of a weak solution u ∈ C([0, +∞) : L<sup>2</sup>(Ω)) can be deduced from the abstract results on Volterra intregro-differential equations with accretive operators.



The main Theorem Sketch of the proof Remarks

# Proof of the existence

- The existence of a weak solution u ∈ C([0, +∞) : L<sup>2</sup>(Ω)) can be deduced from the abstract results on Volterra intregro-differential equations with accretive operators.
  - A. Friedman, On integral equations of the Volterra type, J. Analyse Math., 11, 381-413, 1963.
  - S. Bonaccorsi and M. Fantozzi, Volterra integro-differential equations with accretive operators and non-autonomous perturbations, Journal of Integral Equations and Applications, 18, 437-470, 2006



The main Theorem Sketch of the proof Remarks

# Proof of the existence

- The existence of a weak solution u ∈ C([0, +∞) : L<sup>2</sup>(Ω)) can be deduced from the abstract results on Volterra intregro-differential equations with accretive operators.
- The operator G(u(t)) = −div (|∇u|<sup>p−2</sup>∇u) + β(u) is m-accretive (or, equivalently, maximal monotone) in H = L<sup>2</sup>(Ω), as it is already well known in the literature.
  - J.I. Díaz, Nonlinear Partial Differential Equations and Free Boundaries. Elliptic equations, Research Notes in Mathematics N.106, Vol.1, Pitman, London, 1985.



The main Theorem Sketch of the proof Remarks

### An Energy Method. Case $a_1 > 0$

We define the energy function

$$y(t) := \int_{\Omega} u(x,t)^2 dx = \|u(\cdot,t)\|_{L^2(\Omega)}^2, \qquad (4)$$



The main Theorem Sketch of the proof Remarks

An Energy Method. Case  $a_1 > 0$ 

We define the energy function

$$y(t) := \int_{\Omega} u(x,t)^2 dx = \|u(\cdot,t)\|_{L^2(\Omega)}^2, \qquad (4)$$

multiplying by u and integrating on Ω the equation appearing in (P), we get, due to the Sobolev, Hölder and Young inequalities:

$$\frac{a_1}{2}\frac{dy}{dt} + a_\alpha \int_\Omega \frac{\partial^\alpha u}{\partial t^\alpha}(x,t) \, u(x,t) dx + C \, y(t)^\nu \le 0, \quad (5)$$

for some C > 0 and  $\nu \in (0, 1)$  (this is implied by the hypothesis on  $\sigma$  and p) and for a.e.  $t \in (t_f, +\infty)$ .

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An Energy Method. Case  $a_1 > 0$ 

► Also, we know that [Clement and Prüss,1990] the operator:

$$u \mapsto a_{\alpha} \frac{\partial^{\alpha} u}{\partial t^{\alpha}}$$
 (6)

generates a contraction semigroup in  $L^2(\Omega)$ .



The main Theorem Sketch of the proof Remarks

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▶ So, since  $a_1 > 0$  we get that, for any  $t \ge t_f$ , the application

$$t\mapsto y(t)$$

is non increasing,  $y \in C([t_f, +\infty])$  and  $\frac{d^{\alpha}y}{dt^{\alpha}} \in L^1(t_f, T)$ (indeed, the weak solution is a strong solution too, thanks to the regularity required on  $u_0$  and f).



The main Theorem Sketch of the proof Remarks

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generates a contraction semigroup in  $L^2(\Omega)$ .

Therefore, we are in conditions as to apply Lemma 2, and we get:

$$\begin{cases} \frac{a_1}{2}\frac{dy}{dt} + \frac{a_\alpha}{2}\frac{d^\alpha y}{dt^\alpha}(t) + C y(t)^\nu \leq 0 \quad \text{on } (t_f, +\infty) \\ y(t_f) = Y_0. \end{cases}$$



The main Theorem Sketch of the proof Remarks

An Energy Method. Case  $a_1 > 0$ 

Moreover, since the semigroup generated by the operator (6) is positive [although it is non local] (Clement and Prüss, 1990), we have that:

$$0 \leq y(t) \leq Y(t)$$
 for any  $t \in [t_f, +\infty)$ , (8)

where Y(t) is a supersolution, i.e., Y(t) satisfies the inequality:

$$\begin{cases} \frac{a_1}{2}\frac{dY}{dt} + \frac{a_\alpha}{2}\frac{d^\alpha Y}{dt^\alpha}(t) + C Y(t)^\nu \ge 0 \quad \text{on } (t_f, +\infty) \\ Y(t_f) \ge Y_0. \end{cases}$$
(9)



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(9)

Our conclusion comes from the fact that we can construct Y(t) satisfying (9) and such that Y(t) ≡ 0 ∀ t ≥ t<sub>Y</sub>, for some t<sub>Y</sub> > t<sub>f</sub>.



The main Theorem Sketch of the proof Remarks

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For instance,

$$Y(t) = k \left( t_Y - t \right)_+^{\frac{1}{1-\nu}}$$



for some  $t_Y > t_f$  and some k > 0.

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The main Theorem Sketch of the proof Remarks

## An Energy Method. Case $a_1 = 0$

- Let  $u_{\varepsilon}$  be the solution of  $(\mathcal{P}_{\varepsilon})$  when  $a_1 = \varepsilon$ ,  $\varepsilon > 0$ .
- We can prove that:

$$u_{arepsilon} o u^* \quad ext{in} \ L^2(0,+\infty:L^2(\Omega)) \quad ext{when} \ arepsilon o 0,$$

so the application

$$t\mapsto y^*(t):=\left\|u^*(\cdot,t)\right\|_{L^2(\Omega)}^2$$

is also decreasing.



The main Theorem Sketch of the proof Remarks

An Energy Method. Case  $a_1 = 0$ 

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ightarrow 0,$$

so the application

$$t\mapsto y^*(t):=\|u^*(\cdot,t)\|^2_{L^2(\Omega)}$$

is also decreasing.

▶ Then, we can apply Lemma 2 and write for *y*\*:

$$\left\{ egin{array}{l} rac{a_{lpha}}{2}rac{d^{lpha}y^{*}}{dt^{lpha}}(t)+\mathcal{C}\,y^{*}(t)^{
u}\leq0\quad ext{on}\;(t_{f},+\infty)\ y(t_{f})=\mathcal{W}_{0}. \end{array} 
ight.$$

The main Theorem Sketch of the proof Remarks

An Energy Method. Case  $a_1 = 0$ 

The conclusion, as before, comes now from the fact that we can construct a supersolution W(t) satisfying:

$$\begin{cases} \frac{a_{\alpha}}{2} \frac{d^{\alpha} W}{dt^{\alpha}}(t) + C W(t)^{\nu} \ge 0 \quad \text{on } (t_f, +\infty) \\ W(t_f) = W_0, \end{cases}$$
(11)

and such that  $W(t) \equiv 0 \ \forall \ t \geq t_W$ , for some  $t_W > t_F$ .

• Indeed, let i.e.  $W(t) = h(t_W - t)^{\frac{\alpha}{1-\nu}}$  for some  $t_W > t_f$  and some h > 0.



The main Theorem Sketch of the proof Remarks

### Remarks

The decreasing behavior of the norm:

$$\|u(\cdot,t)\|_{L^{2}(\Omega)}^{2} \leq k(t_{Y}-t)_{+}^{\frac{1}{1-\nu}} \quad \forall t \geq t_{f}, \ \nu \in (0,1)$$
 (12)

when  $a_1 > 0$  is actually the same as when the fractional derivative is not included in the problem ( $\mathcal{P}$ ).

It has to be highlighted that when v > 1 it is well-known that the solution to problem (P) shows an exponential decay at infinity. However our method allows to estimate trough (12)the rate of this decay, which is impossible to achieve with the stabilization methods.

The main Theorem Sketch of the proof Remarks



What is more extraordinary is the decreasing behavior of the norm:

$$\|u^*(\cdot,t)\|^2_{L^2(\Omega)} \leq h(t_W-t)^{rac{lpha}{1-
u}}_+ \quad orall t \geq t_f.$$

when  $a_1 = 0$  as we are dealing with a function W(t) such that  $\frac{d^{\alpha}W}{dt^{\alpha}}(t) \in L^{\infty}(0, +\infty)$  whereas  $W'(t) \notin L^{\infty}(0, +\infty)$  although  $W'(t) \in L^1(0, +\infty)$ .





This work extends the application of the very fine techniques of nonlinear operators on Banach spaces to the case of nonlinear fractional partial differential equations.



# Conclusions

- This work extends the application of the very fine techniques of nonlinear operators on Banach spaces to the case of nonlinear fractional partial differential equations.
- The finite time extinction phenomenon for certain evolution boundary values problems are still valid when the evolution in time is given by an ordinary derivative jointly with a real order differential operator (which is compatible with unbounded, but integrable, first time derivatives).



#### Thank you for your kind attention!

